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Encoder Instructions

SOLID SHAFT 1/4" - 10mm

DESCRIPTION

The Avtron Model AV20 Encoder is a light mill duty speed and position transducer (also known as tachometer or rotary pulse generator). When coupled to a motor or machine, its output is directly proportional to shaft position (pulse count) or speed (pulse rate).

Mechanically the AV20 mounts using industry standard 2" square or round flanges. The AV20 can also be mounted using an optional industry standard face mount bolt pattern.

The AV20 encoder offers 2Ø outputs (A,B) 90° apart for direction sensing. Optional complements $(\overline{A},\overline{B})$ and marker pulse and complement (Z,\overline{Z}) are available; see channel options.

DRIVE INSTALLATION INSTRUCTIONS

The AV20 may be driven via a contact/friction wheel provided the axial spring force is modest, less than 25% of the 100 lb maximum radial load, or (preferably) the AV20 can be coupled to the load. The following means of coupling are acceptable when properly installed: Direct Coupling, Timing Belt/Pulleys.

With a direct drive, use a flexible, insulated disc coupling and align the shafts as accurately as possible. The encoder should not be subjected to any axial thrust. Overhung loads should also be minimized. Installations using timing belts/pulleys should have just enough belt tension to eliminate belt sag. Excessive tension will shorten belt and bearing service life. If a rubber slinger disc is used, position it on the shaft so it will rotate freely.

CAUTION

Do not force or drive the coupling onto the shaft or damage to the bearings may result. The coupling should slide easily on the shaft. Remove nicks and burrs if necessary. Consider driving shaft endplay when positioning coupling.

Equipment Needed for Installation						
Provided	Optional	Not Provided				
AV20 Encoder	Mating MS Cable Connector	AV20 Face Mounting Screws (see table below and drawing on last page for sizes) Thread Locker (Loctite 242 recommended)				
		Adapter Flange Shaft Coupling (Insulated style recommended)				
		Dial Indicator Gauge				

For more details on alignment specifications, measurement techniques, and special considerations in specifying and installing drive components, refer to separate installation instructions in the Avtron ENCODER HÁNDBOOK.

FACE and FLANGE MOUNTING INSTRUCTIONS

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- Disconnect power from equipment and encoder cable.
- 2) Use dial indicator guage to verify the motor/load total indicated shaft runout <0.002" [0.05mm].
- 3) Apply anti-seize compound to inner circumference of coupling (both motor and encoder side).
- Loosen set screws in coupling and apply thread locker to set 4) screws.
- Place coupling on motor/load shaft, inserting to depth per 5) manufacturer's instructions.
- Attach coupling to motor/load shaft using set screws per 6) manufacturer's instructions.

AV20 PA	RT NUMBERS AI	ND AVAILA	BLE OP1	TIONS						
Mount	PPR*	Line Driver	Shaft Size	Connector Options	Wiring	Mounting Style	Face/Bolt Pattern	Seals	Channels	Special Features
AV20		 5-28V (7272) 5-28V, open collector (7273) 5-28V in, 5V out (7272) 	0-Non-std. <u>With Flat</u> A- 0.25" B- 0.375" C- 10mm <u>Without Flat</u> N- 0.25" P- 0.375" R- 10mm	W- 18" cable (pigtail)	A- Side	1- Sq. Flange 2.06" w/ 1.25" male pilot 2- Rnd. Flange 2.0" w/ 1.25" male pilot 3- Sq. Flange 2.06" w/ 1.181" female pilot 4- Rnd. Flange 2.0"	X- None 5- 4x 6-32 @ 2" 6- 4x 10-32 @ 1.625" 7- 3x 4-40 @ 1.5"	A- Shaft Sealed ^{**} B- Bearing Sealed X- None^^	With Comp. A- A,Ā,B,Ē Z,Z̄*** B- A,Ā,B,Ē D- A,Ā Without Comp. E- A, B, Z F- A, B	000- None 00W- Con- nector on 18" cable: Use w/ Option "T"-"U" 9xx- Specify cable length xx=feet (use w/ Option "W")
E- 360 6- 2540 Q- 500 7- 3600			Connector Options							
	R- 512 0- Special S- 600			10 Pin MS	Mo	6 Pin MS	7 Pin M	s	Mounted on 1 8 Pi	8" cable (00W)
* up to 16,384 PPR available ** recommended, N/A with Mounting Styles "3" & "4". *** N/A with MS 6 or 7 Pin Connector.			A- B- ing) C-	A- w/o plug (std. phasing) B- w/o plug (reverse phas- ing) C- w/ plug (std. phasing) G-		plug (std. phasing) plug (reverse phas- lug (std. phasing)	J- w/o plug (std. phasing) K- w/o plug (reverse phasing) M- w/ plug (std. phasing) N- w/ plug (reverse phasing)		T- w/o plug (Turck Pinout) U- w/o plug (US Pinout)	

D- w/ plug (reverse phasing) H- w/ plug (reverse phasing)

N/A with MS 6 or 7 Pin Connector.

^^ not recommended for industrial applications

All dimensions are in inches [millimeters].

Specifications and features are subject to change without notice.

- 7) Slide encoder shaft into other side of coupling. DO NOT FORCE.
- Ensure face on mounting flange matches and aligns with encoder face precisely.
- Apply thread locker to face mounting screws or flange mounting bolts.
- 10) Align bolt holes of encoder and flange, thread in screws.
- 11) Tighten set screws on encoder side of coupling.

WIRING INSTRUCTIONS

CAUTION

Be sure to remove power before wiring the AV20 Encoder.

Be sure to ground the cable shield: It can be connected to case ground at the encoder, or grounded at the receiving device, but should not be grounded on both ends.

If necessary, case ground can also be provided through a separate wire. (Not available for 6-pin connectors: options "E", "F", "G", "H"). Be certain not to ground the case ground wire if the encoder is already grounded by mechanical mounting or coupling.

For bidirectional operation of the AV20 Encoder, proper phasing of the two output channels is important. For models with A and B output channels, Phase A channel leads Phase B channel for clockwise shaft rotation as viewed from the rear of the encoder for the standard wiring options. Follow instructions under corrective installation as needed to reverse the direction of output or purchase AV20 with reverse phasing (options "B", "D", "F", "H", "K", "N").

CORRECTIVE ACTION FOR PHASE REVERSAL

- 1) Remove power.
- Exchange wires on cable, either at encoder cable end, or at speed controller end (but not both):
 - a.) Single Ended 2 Phase Wiring (see wiring diagram) Exchange A and B at the user end of the wires.
 - b.) Differential 2 Phase Wiring (see wiring diagram) Exchange either A with A in the phase A pair OR B with B in the phase B pair but NOT both.
- 3) Apply power.
- Verify encoder feedback is correct, using hand rotation of shaft, or jog mode of the speed controller.

Interconnecting cables specified in the wire selection chart below are based on typical applications. Refer to the system drawing for specific cable requirements where applicable.

Physical properties of cable such as abrasion, temperature, tensile strength, solvents, etc., are dictated by the specific application. General electrical requirements are: stranded copper, 22 thru 16 gauge, each wire pair individually shielded with braid or foil with drain wire, 0.05 uF maximum total mutual or direct capacitance, outer sheath insulator. See Wire Selection Chart below for some suggested cables.

*Maximum cable length (and line driver selection) is limited by several factors: line driver protection, maximum RPM, PPR, output voltage and cable capacitance. The open collector driver (option 2) is much more heavily limited by output frequency on long cable runs, and is not recommended for new applications.

SPECIFICATIONS -

ELECTRICAL

A. Operating Power (Vin) 1. Volts	. See Line Driver Options	
2. Current	50mA, no load	
B. Output Format	. See Channel Options (A,Ā,B available)	,Ē,Z,Ż
C. Signal Type	. Incremental, Square Wave, & Duty Cycle	50% ±10%
D. Direction Sensing	. Phasing with respect to rota viewed from the back of the	tion as encoder
Connector options "A	" "O" "E" "O" "I" "M" "II"	9 "\ <i>NI</i> ", (XA
Connector options A	ι, C, Ε, G, J, Μ, Ο,	α W:0A
leaus	OR for OW rotation	
nhooing)	OB IOF CW FOLALION	(510.
phasing).	" "D" "F" "I" "IZ" "N" 0 "T	
ØB for	, "D", "F", "Η", "Κ", "Ν", & "Τ	: WA leads
	CCW rotation (Beverse phase	sina)
F Transition Separation	15% minimum	,g/.
E. Frequency Range	0 to 125kHz	
	1 - 3600 standard (for other P	PR noode
G. 1111	up to 16 284 consult factory)	i n neeus
	Soo Line Driver Options	
	. See Line Driver Options	
MECHANICAL		
A. Acceleration	.6,000 RPM/Sec.	
B. Speed	. 6,000 RPM max. (for higher	RPM
needs,		
	Consult Factory).	
C. Shaft Diameter	.0.25" to 0.394" [6.35mm to 1	0mm1
D. Shaft Loading	. up to 100 lbs [45 kg]. axial o	r radial
E. Starting Torgue @ 25C.	.2.5oz in max. [0.018n-m]	
5 1 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	(1.0oz [0.007n-m] in w/o sea	ls)
F. Weight	.0.575 lbs. [260g]	

ENVIRONMENTAL

A. Enclosure Rating NEMA 4, 13, IP65 (dust and water tight, not for immersion).

- B.Operating Temp.....-40° to +100°C

LINE DRIVER OPTIONS

		Output Options			
		1 2		4	
Output Type		Differential Line Driver	Open Collector	Differential Line Driver, 5V fixed	
Line Driver		7272	7273	7272	
Voltage Input (Vin)		5-28VDC	5-28VDC	5-28VDC	
Protection	Reverse Voltage	Yes	Yes	Yes	
	Transient	Yes	Yes	Yes	
	Short Circuit	Yes	Yes	Yes	
Maximum Cable length*		5V 1000 ft 12V 500 ft 24V 200 ft	see note*	200 ft	



For Connector Option "W", unused connections must be insulated to prevent accidental contact.

* NOTE: Connecting Case Ground is optional, and is not recommended if the encoder is already grounded by mechanical means or coupling.

BELDEN ALPHA 2 PAIR 9368 6062C 3 PAIR 9369 6063C

9388

9389

6064C

6066C

4 PAIR

6 PAIR





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REV: 04-12-2022